Air-to-Air Avionics Integration

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What Passenger Demand Will Cause

- More on-time performance (no later than 30 minutes)
- Faster airport throughput on foot
- Reasonable departure times from hubs (the 8 and 5 o'clock hours)
- Greater options to major markets with significant competition
- Service to smaller communities at a cost on the order of the value of time (drive or fly decision)



The consequences:

- Departure time compression
- Greater fleet mix
- Greater city-pair demand
- Need for greater airport efficiencies and throughput

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NGATS Capabilities

Wants

- Visual capacities in instrument conditions
- Super density airport operations
- Tailored arrivals
- Reduced separation
- 4-D trajectory-based separation
- 3X capacity

Needs

- Equivalent visual separation pilot spacing
- Reduced variability
- Increased arrivals per hour
- Separation assurance
- Intent needed for 4-D
- 3X capacity



Intelligent Highways

Following truck uses Doppler radar, GPS, lane sensors and data link to "lock on" to the leader

Benefit - trucker rests while in trail mode

Lead is exchanged during travel
Other vehicles not permitted
between lead and following
trucks

An integrated travel management system





Why Not Fly In Formation?

- Military formation flying is a visual flight maneuver
- Formation flying in weather is done by lead with wingmen maintaining visual spacing
- Is commercial civil aviation ready for formation flying?



4X Capacity



The Views From Seat 18A?

What is needed is something greater than visual contact formation flying as an all-weather capability designed to:

- **■** Increase situational awareness
- Reduce workload
- Provide safety margins greater than that possible with air traffic controllers
- Deliver significant capacity gains with comfort, convenience, and safety





Paired Flight

What if two aircraft could pair up and fly together with performance matched to all phases of flight?

Why not allow the aircraft to talk to each other using flight

command inputs?



- Outputs of one aircraft become inputs to the other
- Changes in heading, speed, power, configuration and touch down are known instantly to correct paired performance

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Electronic Formation

What if pilots had shared intent information from inputs to the autopilot of another aircraft?

What if one aircraft could "lock on" to another aircraft and maintain spacing during station keeping - including the approach and landing?



- Significant reductions in separation variability and inter-arrival variability
- Controlling one aircraft with another in e-formation



Why e-Formation

- Increase capacity and reduce separation en route and in oceanic airspace
- Add precision separation with reduced interarrival variability on approach
- Enable wake vortex avoidance in instrument weather conditions
- Enable multiple aircraft on the runway
- Provide pilots with automated aids to reduce workload during station keeping
- Provide controllers with separation assurance
- Provide 2X capacity with 1X procedures



Air-to-Air Avionics Exchange

The sharing of information between aircraft that provides actual commands for the flight controls and configuration of the leading aircraft

This information set is called "micro-intent" and is well beyond the current scope of ADS-B intent

"Micro-intent" actually flows from one aircraft (leader) and is processed to control flight of the following aircraft

Electronic formation flying without visual contact



Micro-Intent Data Sources

Flight Management System

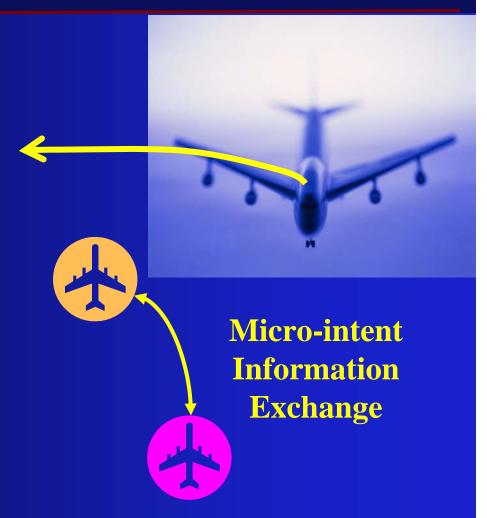
Flight Data Recorder Bus information

Flight control input commands

Weight on gear

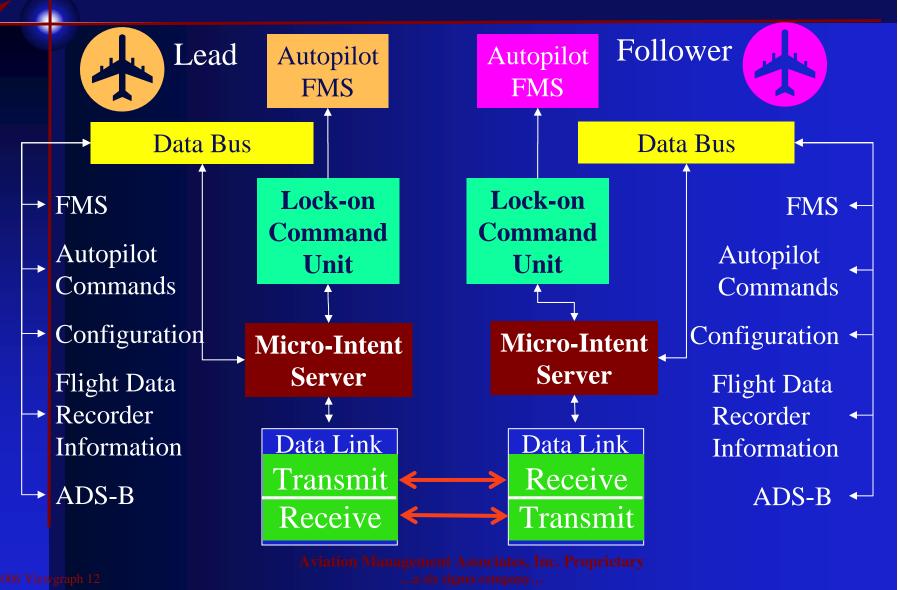
GNSS position information

Aircraft configuration sensors (spoilers - NOW)





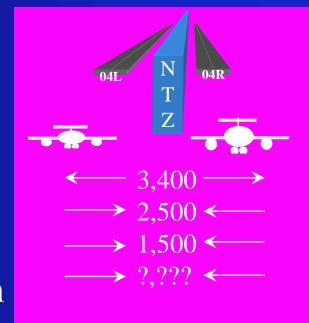
Notional Architecture





Closely-Spaced Parallels

- 3,400 feet with PRM and now multilateration
- 2,500 feet with aircraft-to-aircraft ADS-B
- 1,500 feet with RNP and airto-air information exchange in a paired approach
- ?,??? feet with micro-intent

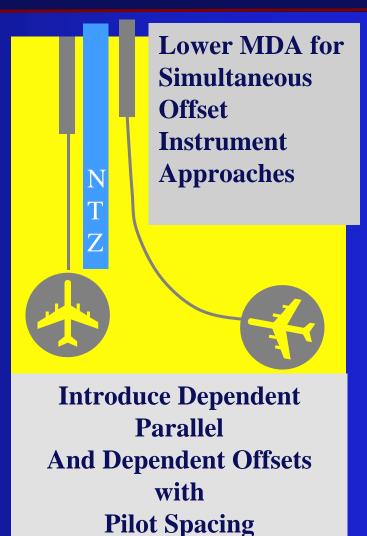


Reduced Lateral
Separation
For Closely Spaced
Parallel Approaches



Offset Instrument Approaches

- Lowering minimum descent altitudes where the offset must transition from instrument to visual
- Opening up more runways to the procedures
- Creating increased pilot and controller confidence with "super dense" airport operations

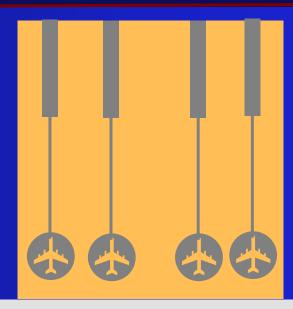


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Trips and Quads

- How would you fly a four aircraft missed approach?
- Air-to-air avionics integration provides micro-intent with mutual input to aircraft autopilots
- "locked on" for the go



Quadruple Arrival and
Departure Streams with
Common Situational
Awareness and Ability to
Manage Multiple Missed
Approaches Through
E-Visual Operations



Paired Oceanic Crossings

Leader Follower













5 miles ← 30 miles ← 30 miles

Separation established by ATC Maintained by station keeping



IMC Wake Avoidance

Lock-on for offset vertical glide slope and verified touchdown point of lead aircraft (weight on the wheels position report)



Smaller Aircraft touch down longer than larger aircraft





Two on the Runway

Knowing current rolling position and deceleration of lead aircraft and nosewheel steering input for confirmation

Distance between follower and leader at touchdown of follower





ADS-B provides the "picture" micro-intent the safety margin

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Paired Departures

- Single runway departure spacing control of variability
- Single runway pairing for en route city pairs
- Multiple runway aircraft join-ups for paired en route
- Paired passing on climb out





e-Formation Separations

3-5 miles en route

5 miles paired in oceanic airspace

Parallel approaches to 750 feet extended runway centerline

Vertical stacking for wake avoidance

Two or more aircraft on the runway

Passing maneuvers for mixed Mach operations

Separation assurance through station-keeping

Visual capacities through reductions in inter-arrival variability

Lower cockpit workload





Far Fetched?

Consider DARPA flocking research for UAV missions

Consider intelligent highways

Consider the possibilities of air-to-air avionics integration

